

C10
B2
1. (Twice Amended) A sensor assembly for use in an elastomeric material, the assembly comprising:

a first pair of sensors disposed along a first pair of respective planes that intersect, each of said first sensors deforming in response to a force in a first direction and generating a corresponding output;

a second pair of sensors disposed along a second pair of respective planes that intersect, each of said second sensors deforming in response to a force in a second direction and generating a corresponding output; and

wherein the force in the first direction is equal to the difference between the outputs of said first sensors, and the force measured in the second direction is equal to the difference between the outputs of said second sensors.

C2
B2
10. (Amended) A three-axis sensor assembly embedded in an elastomeric material, the sensor comprising:

a first sensing element generating a first output indicative of a strain in a first direction applied directly to said first sensing element;

a second sensing element generating a second output indicative of strain in a second direction orthogonal to said first direction applied directly to said second sensing element; and

wherein the sum of said first and second outputs is indicative of strain in a third direction orthogonal to both the first direction and the second direction.

11. (Amended) A sensor assembly embedded in an elastomeric material, said sensor assembly comprising:

a pair of first strain sensors disposed on first opposed faces of a flexible pyramid-shaped body, said first strain sensors detecting a force in a first direction; and

wherein said first strain sensors generate, substantially in real-time, corresponding output signals in response to the force in the first direction, substantially in real-time, and wherein the force in the first direction is generally equal to the difference between the output signals of said first strain sensors.

C3
30. (Twice Amended) A process of embedding a sensor in an elastomeric material, the process comprising:

providing a three-axis sensor assembly including two pairs of strain gauges, a first pair disposed on first opposed faces of a pyramid-shaped body so as to directly detect strain in a first direction, and a second pair disposed on second opposed faces of the pyramid-shaped body so as to directly detect strain in a second direction; and

adjusting the aspect ratio of the pyramid-shaped body to a sensitivity of the three-axis sensor.

C4
45. (Amended) A process of embedding a sensor in an elastomeric material, the process comprising:

providing a three-axis sensor assembly including first and second pairs of strain sensors, the first pair disposed on first opposed faces of a pyramid-shaped body, and the second pair disposed on second opposed faces of the pyramid-shaped body so as to detect strain in a first direction substantially in real-time, and the second pair disposed on second opposed faces of the pyramid-shaped body so as to detect strain in a second direction substantially in real-time; and

placing the sensor assembly in the elastomeric material when the elastomeric material is in an uncured state.

C5
69. (Amended) A three-axis sensor assembly embedded in an elastomeric material that measures strain forces on the elastomeric material, the sensor assembly comprising:

a three-axis sensor assembly including two pairs of strain sensors, a first pair disposed on first opposed faces of a pyramid-shaped body so as to deform in response to strain in a first direction, and a second pair disposed on a second opposed faces of the pyramid-shaped body so as to deform in response to strain in a second direction;

a printed circuit responsive to the outputs of said strain sensors to generate a corresponding signal indicative of the corresponding strain acting on the elastomeric material; and

wherein the sensor assembly is electrically coupled to the printed circuit.